

An Evolutionary View on Reversible Shift-invariant Transformations

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Shift-invariant Transformations and Cellular Automata

Search of Reversible CA with GA and GP

Experiments

Conclusions

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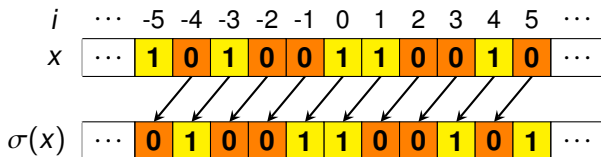
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Shift-invariant Transformations

- ▶ Let $x \in \{0, 1\}^{\mathbb{Z}}$ be a *bi-infinite binary string*
- ▶ The *shift operator* $\sigma : \{0, 1\}^{\mathbb{Z}} \rightarrow \{0, 1\}^{\mathbb{Z}}$ is defined as:

$$\sigma(x)_i = x_{i+1} \quad , \quad \text{for all } x \in \{0, 1\}^{\mathbb{Z}}, i \in \mathbb{Z}$$



- ▶ A mapping $F : \{0, 1\}^{\mathbb{Z}} \rightarrow \{0, 1\}^{\mathbb{Z}}$ is *shift-invariant* if it commutes with the shift operator, that is

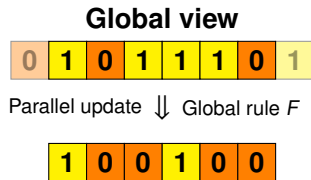
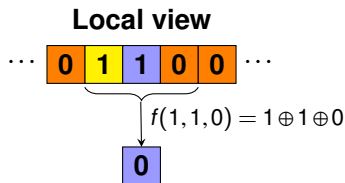
$$F(\sigma(x)) = \sigma(F(x)) \quad , \quad \text{for all } x \in \{0, 1\}^{\mathbb{Z}}$$

Cellular Automata (CA)

Definition (Periodic Boolean Cellular Automata – CA)

A finite binary array of n cells, where each cell x_i updates its state by applying a *local rule* $f : \{0, 1\}^d \rightarrow \{0, 1\}$ to the *neighborhood* $\{x_{i-\omega}, \dots, x_i, \dots, x_{i-\omega+d-1}\}$ with *periodic boundary conditions*

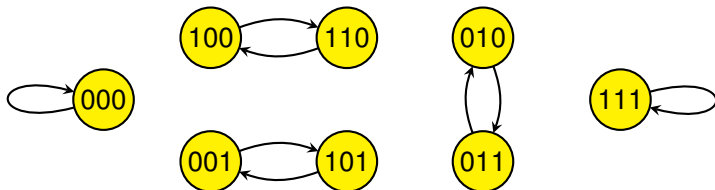
Example: $n = 6$, $d = 3$, $\omega = 1$, $f(x_{i-1}, x_i, x_{i+1}) = x_{i-1} \oplus x_i \oplus x_{i+1}$



Reversible CA

- ▶ A CA is *reversible* (RCA) if its global rule $F : \{0, 1\}^n \rightarrow \{0, 1\}^n$ is *bijective* and the inverse map F^{-1} is also a CA [Hedlund69]
- ▶ Interesting for applications in *reversible computing* and *cryptography* [Mariot19]

Example: $n = 3$, $d = 3$, $\omega = 0$, $f(x_i, x_{i+1}, x_{i+2}) = x_i \oplus x_{i+1} \cdot x_{i+2} \oplus x_{i+2}$



- ▶ Local rules resulting in RCA for every size n of the array are also called *locally invertible* [Daemen95]

Marker CA

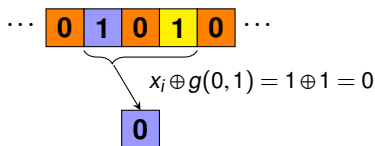
- ▶ The local rule f of marker CA is defined as follows:

$$f(x_{i-\omega} \cdots x_{i-1} x_i x_{i+1} \cdots x_{i-\omega+d-1}) = x_i \oplus g(x_{i-\omega} \cdots x_{i-1} x_{i+1} \cdots x_{i-\omega+d-1})$$

- ▶ Equivalently: the *support* of g defines the *markers* for which the central cell *flips* its state

Example: $d = 3$, $\omega = 0$, $f(x_i, x_{i+1}, x_{i+2}) = x_i \oplus x_{i+1} \cdot x_{i+2} \oplus x_{i+2}$

x_{i+1}	x_{i+2}	$g(x_{i+1}, x_{i+2})$
0	0	0
1	0	0
0	1	1
1	1	0

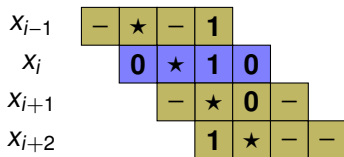


Marker: 01 \Rightarrow ★01 **Flipping landscape**

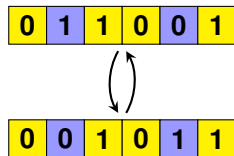
Conserved Landscape Marker CA

- ▶ *Conserved Landscape*: each cell in a flipping landscape must be in the *same* landscape after applying the CA global rule

Example: $d = 4$, $\omega = 1$, Landscape: $0 \star 10$



Landscape tabulation



Example of orbit of period 2

- ▶ A landscape is conserved if it is *incompatible* with all its *neighborhood landscapes* [Toffoli90]
- ▶ **Question:** How to turn the search of conserved landscape marker CA into an optimization problem?

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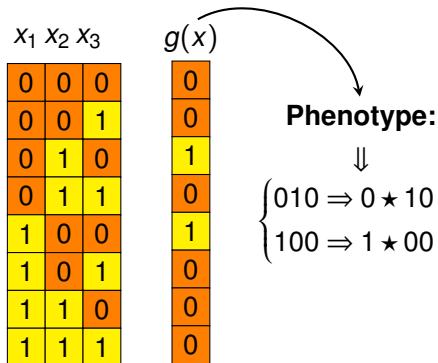
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Genotype Encoding – GA

- ▶ *Phenotype*: the set of markers in the generating function g
- ▶ *GA Genotype*: Bitstring $g(x)$ corresponding to the output column of the *truth table* of g

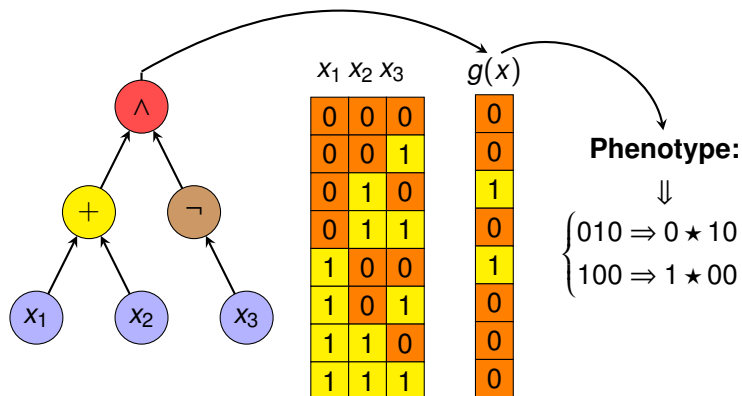
Example: $d = 4, \omega = 1, g : \{0, 1\}^3 \rightarrow \{0, 1\}$



Genotype Encoding – GP

- ▶ *GP Genotype*: Boolean tree
- ▶ The truth table $g(x)$ is synthesized from the tree [Mariot18]

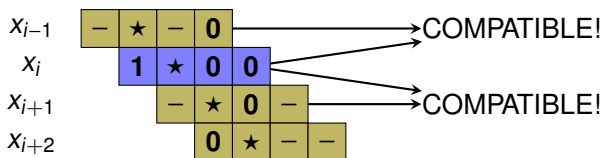
Example: $d = 4$, $\omega = 1$, $g : \{0, 1\}^3 \rightarrow \{0, 1\}$



First Fitness Function

- ▶ **Objective:** minimize the number of neighborhood landscapes that are compatible with each landscape in g

Example: $d = 4$, $\omega = 1$, Landscape: $1 \star 00$



- ▶ **Fitness function:** Loop over all landscapes in the support of g and count the compatible neighborhood landscapes

$$fit_1(g) = \sum_{i,t \in [k], j \in [d-1]_\omega} comp(M_{i,j}, L_t)$$

Second Fitness Function

- ▶ **Objective:** maximize the Hamming weight of g
- ▶ This criterion is relevant in cryptography: the higher the Hamming weight of g , the higher the nonlinearity of the CA

Example: $d = 4, \omega = 1, g : \{0, 1\}^3 \rightarrow \{0, 1\}$

$$g(x) = \begin{array}{|c|c|c|c|c|c|c|c|} \hline 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ \hline \end{array}$$



Hamming weight: 2

- ▶ **Fitness function:** Count the number of 1s in $g(x)$

$$fit_2(g) = |supp(g(x))|$$

Exhaustive Search up to $d = 6$

- ▶ No. of generating functions of $d - 1$ variables: $\#\mathcal{P}(d) = 2^{2^{d-1}}$
- ▶ We performed an exhaustive search of all conserved landscape rules up to $d = 6$, with $\omega = \lfloor \frac{d-1}{2} \rfloor$

d	2^{d-1}	$\#\mathcal{P}(d)$	#REV	Weights
3	4	16	0	–
4	8	256	1	1
5	16	65536	10	1,2
6	32	$4.3 \cdot 10^9$	46	1,2,3

- ▶ The number of conserved landscape rules is *really small* wrt the number of generating functions
- ▶ The possible Hamming weights are *really low* wrt to the length of the truth table of g

- ▶ **RQ1:** Given the limited number conserved landscape rules, is it difficult for GA and GP to find them?
- ▶ **RQ2:** Do there exist conserved landscapes rules of a larger diameter and with higher Hamming weight?
- ▶ **RQ3:** Is there a trade-off between the reversibility of a marker CA rule and its Hamming weight?

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Common Parameters:

- ▶ Problem instances: diameters $7 \leq d \leq 13$
- ▶ Termination condition: 500 000 fitness evaluations
- ▶ Each experiment is repeated over 30 independent runs
- ▶ Selection operator: steady-state with 3-tournament operator

GA Parameters:

- ▶ Population size: 30 individuals
- ▶ Mutation probability: $p_m = 0.2$

GP Parameters:

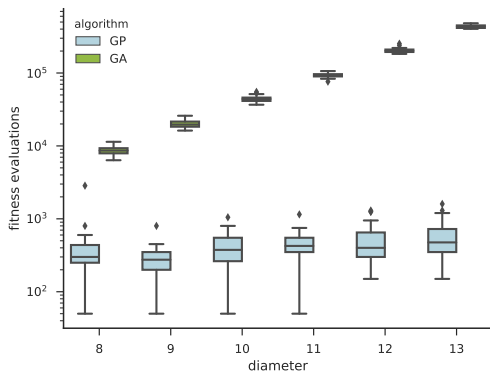
- ▶ Boolean operators: AND, OR, XOR, XNOR, NOT, IF
- ▶ Population size: 500 individuals
- ▶ Mutation probability: $p_m = 0.5$

We employed three different optimization approaches to investigate the research questions:

- ▶ *Single-objective Optimization* only of the reversibility property with GA and GP, by minimizing fit_1
- ▶ *Multi-objective Optimization* with GP, by minimizing fit_1 and maximizing the Hamming weight fit_2
- ▶ *Lexicographic Optimization* with GP, by first minimizing fit_1 and then maximizing fit_2 while retaining reversibility

Single-Objective GA and GP

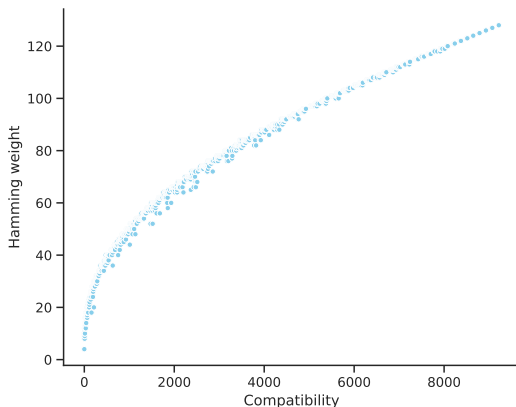
- ▶ **Main finding:** *both GA and GP converge to an optimal solution over all experimental runs*



- ▶ However, the number of fitness evaluations required by GA scales exponentially with the number of variables

Multi-Objective GP

- ▶ We used Multi-objective GP to approximate the Pareto fronts of reversibility vs. Hamming weight



- ▶ **Main finding:** *The more a marker CA rule is reversible, the lower its Hamming weight must be*

Lexicographic GP Optimizer

- ▶ We compared the Hamming weights and distinct solutions achieved by lexicographic GP with MOGP, SOGP and SOGA

d	SOGA			SOGP			MOGP			LEXGP		
	UHW	MHW	USol	UHW	MHW	USol	UHW	MHW	USol	UHW	MHW	USol
8	5	6	30	4	8	27	4	10	24	5	10	47
9	6	7	30	4	16	29	2	20	22	8	20	60
10	7	11	30	3	16	30	4	32	48	6	28	65
11	9	15	30	3	32	29	6	56	40	6	56	64
12	11	23	30	4	64	30	4	72	29	7	80	71
13	12	29	30	2	64	29	4	128	50	7	160	73

- ▶ **Main finding:** *Lexicographic GP achieves the best trade-off among number of distinct optimal solutions, highest and distinct Hamming weights achieved*

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Summing up our findings:

- ▶ **RQ1:** Despite the small size of the optimal solution set, GA and GP always converge to conserved landscape rules (although GP is far more efficient than GA)
- ▶ **RQ2:** Conserved landscape rules seem to be characterized by low Hamming weights with respect to their size (thus, they are not interesting for cryptographic purposes)
- ▶ **RQ3:** The Pareto fronts suggest that the closer a rule is of the conserved landscape type, the lower its Hamming weight is

Several directions open for further research:

- ▶ Investigate the performance gap between GA and GP, by performing fitness landscape analysis
- ▶ Consider marker GA rules with *partially overlapping* landscapes, which may be more interesting for cryptography
- ▶ Find a theoretical explanation for the trade-off between reversibility and Hamming weight observed on the Pareto fronts.

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